



Joint Agency Commercial Imagery Evaluation
NASA • NGA • NOAA • USDA • USGS



Long Term Geometric Stability of the SkySat Constellation

Dr. Byron Smiley, 19 Sep 2018

Mercator Projection

outline

- constellation update
- high precision methods
 - description
 - results
- low precision methods
 - motivation
 - description
 - comparison to high precision results
 - current results



Khe Solar One, South Africa



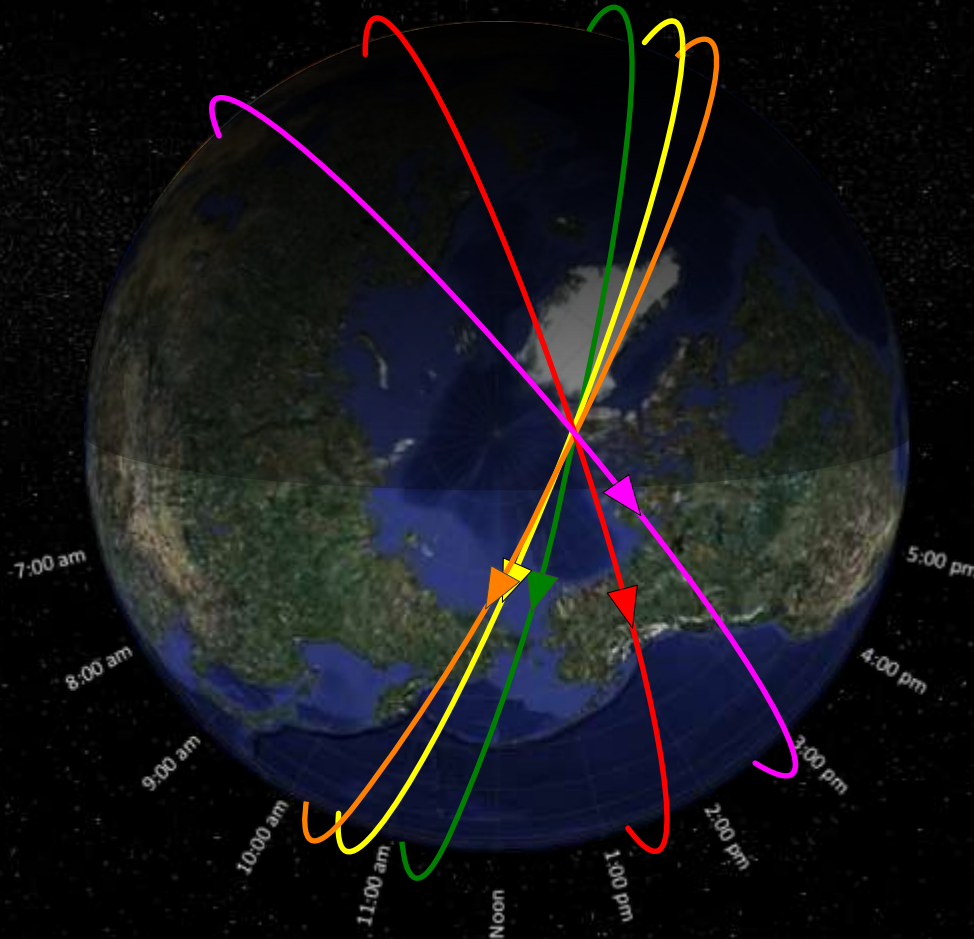


SkySat constellation update

Iguazú National Park, Brazil – September 23, 2016



Planet has 13 SkySats, with 2 more coming

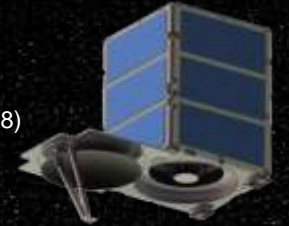


SkySat-1

- launched on Dnepr, 21 Nov 2013
- **~570 km, 11:03am** (as of Sep 2018)

SkySat-2

- launched on Soyuz, 8 Jul 2014
- **~620 km, 2:36pm** (as of Sep 2018)



“generation A”

SkySat-3

- launched on PSLV, 22 Jun 2016
- **~495 km, 10:34am** (as of Sep 2018)

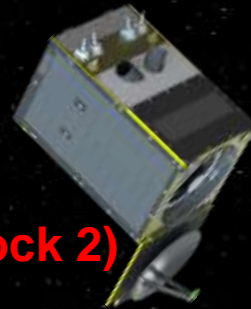
“generation C”

SkySat-4 5 6 7 (Block 1)

- launched on Vega, 16 Sep 2016
- **~495 km, 10:15am** (as of Sep 2018)

SkySat-8 9 10 11 12 13 (Block 2)

- launched on Minotaur, 31 Oct 2017
- **~500 km, 1:07pm** (as of Sep 2018)



SkySat-14 15 (remaining Block 2)

- expected launch on a SpaceX Falcon 9, mid-Nov 2018
- **~500 km, 1:00pm to match Block 2**



high precision methods

a very brief review

Lake Simcoe, Ontario, Canada – February 23, 2016



absolute geolocation accuracy is measured with GCPs

38 geocal sites

more

the accuracy of the GCPs (< 1 meter) makes it high precision!

CompassData

GCP sitename

GCPs

Fairbanks, Alaska 11

Helsinki, Finland 10

Fort McMurray, Alberta 9

Calgary, Alberta 14

Whistler, British Columbia 5

Aix-en-Provence, France 8

Manchester, New Hampshire 4

Detroit, Michigan 7

Zaragoza, Spain 7

Los Angeles, California 13

Phoenix, Arizona 65

Tucson, Arizona 3

Amman, Jordan 8

Gran Canaria, Spain 5

Manatee & Sarasota County, Florida 7

Jeddah, Saudi Arabia 7

Kona, Hawaii 5

Mexico City, Mexico 13

Aden, Yemen 8

San Jose, Costa Rica 7

Abuja, Nigeria 5

Negombo, Sri Lanka 7

Piura, Peru 9

Yogyakarta, Java 9

Recife, Brazil 5

Darwin, Australia 4

Ndola, Zambia 5

Cairns, Australia 15

North West Cape, Australia 4

Alice Springs, Australia 24

Gaborone, Botswana 4

Perth, Australia 10

Adelaide, Australia 5

Canberra, Australia 10

Hobart, Tasmania 9

Queenstown, New Zealand 8

Balmaceda, Chile 8

Punta Arenas, Chile 8

GCPs are marked using a MATLAB codebase

Aden GCP

YAA104

marked in 9 frames

(ground scan speed and frameRate
determine this)

full resolution detector image



the accuracy of the marking (<1 pixel) makes it high precision!

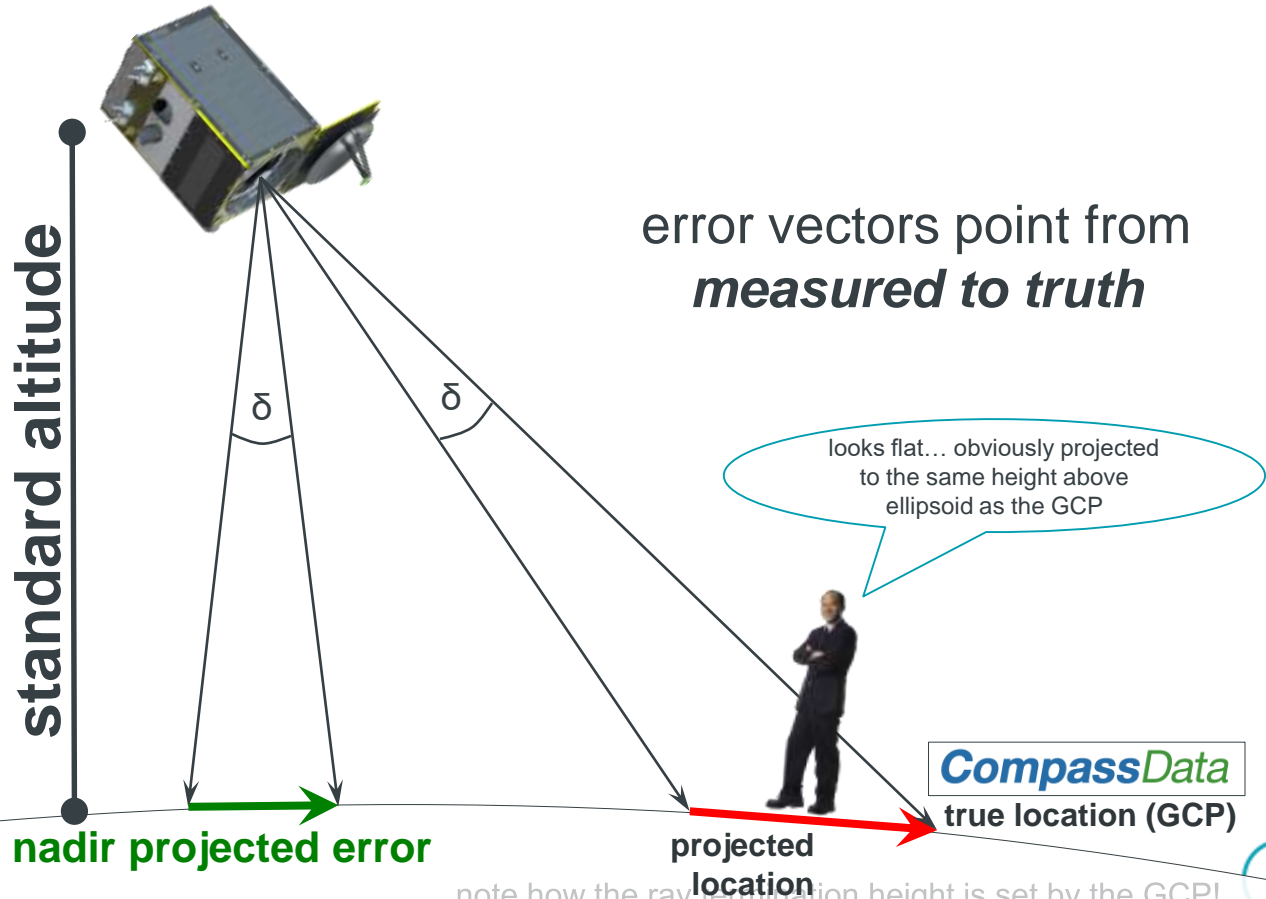


geolocation errors are nadir projected during analysis

nadir projection is used to compare collects with different off nadir angles

SkySat	standard altitude (km)
1	600
2	635
3...13	510

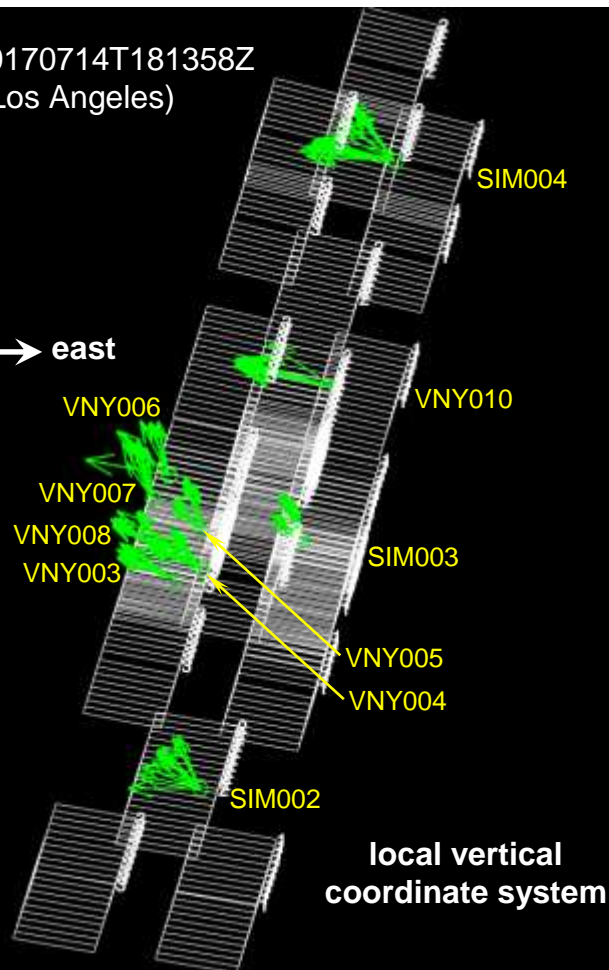
scaling factors **not** updated over time, to keep past results fixed



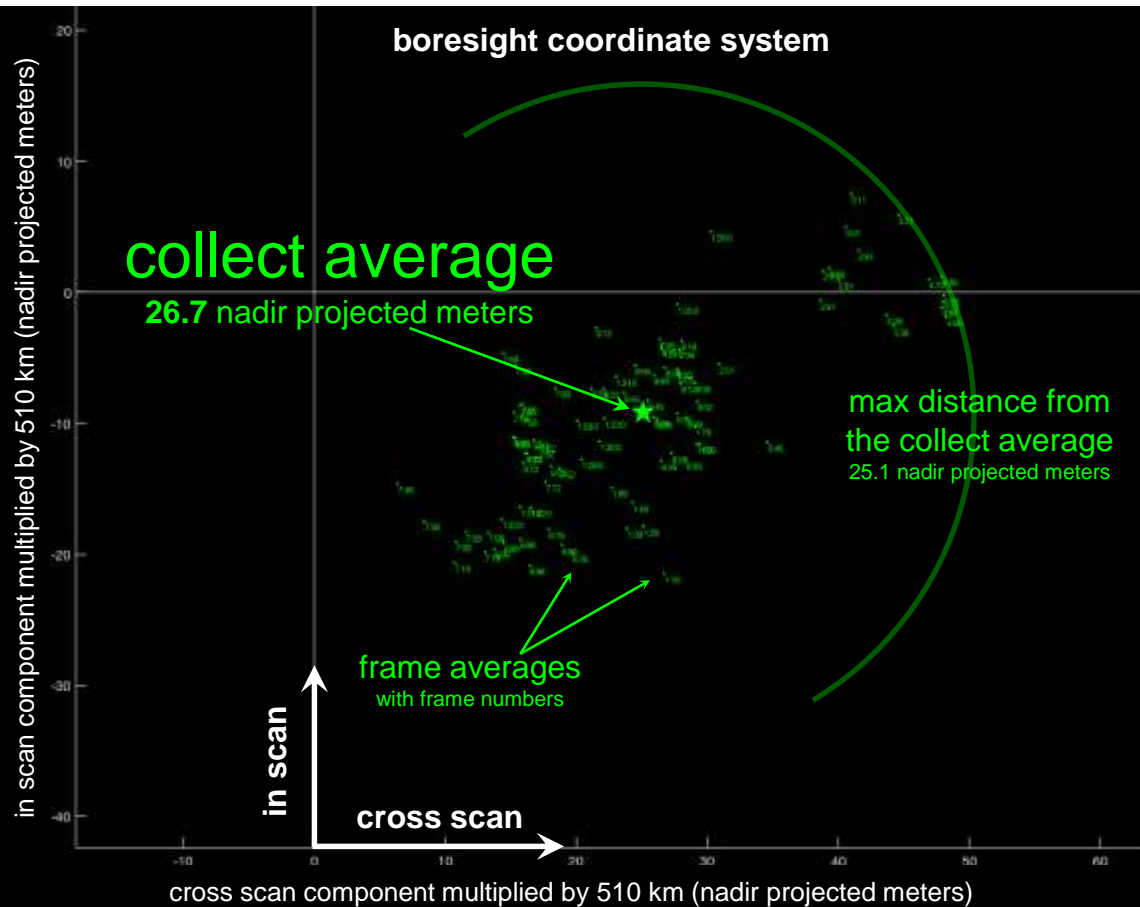
geolocation error changes as the frames roll in

s03_20170714T181358Z
(Los Angeles)

north
east



local vertical
coordinate system



high precision results

for selected SkySats

Valle de la Luna, Argentina – July 19, 2016



geometric stability is the norm

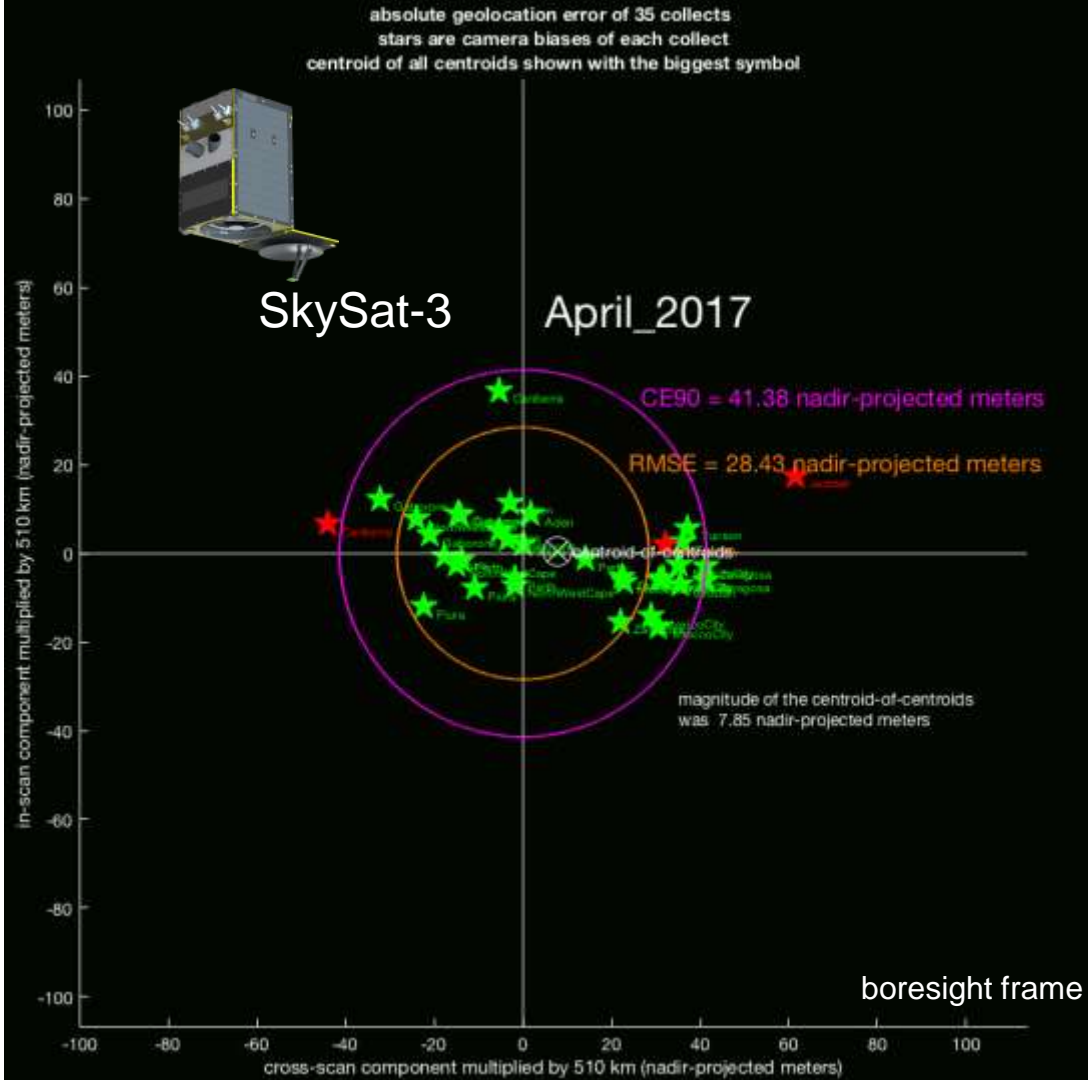
13 months of high precision monitoring reveal that C generation SkySats **are stable, rarely perturbed by anomalies.**

rarely = sometimes (!)

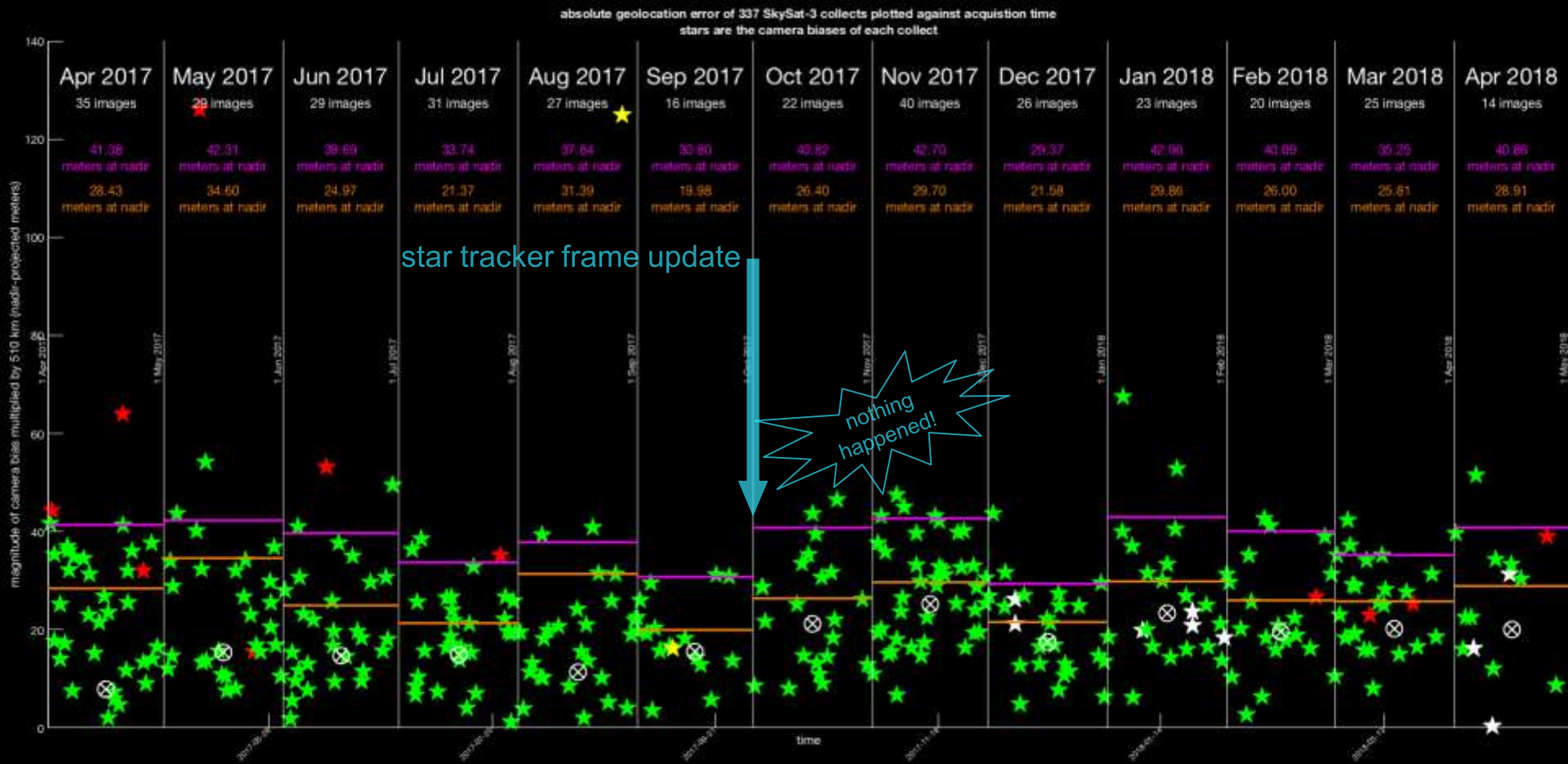
13 months of SkySat-3, ending in April 2018

collect average star color	meaning
white	tracker lock unknown
green	dual tracker lock
yellow	tracker A only
blue	tracker B only
red	"freaky", "unsettled" (obvious Kalman filter problems)

*13 months of good behavior!
no sudden increases in bias or CE90*



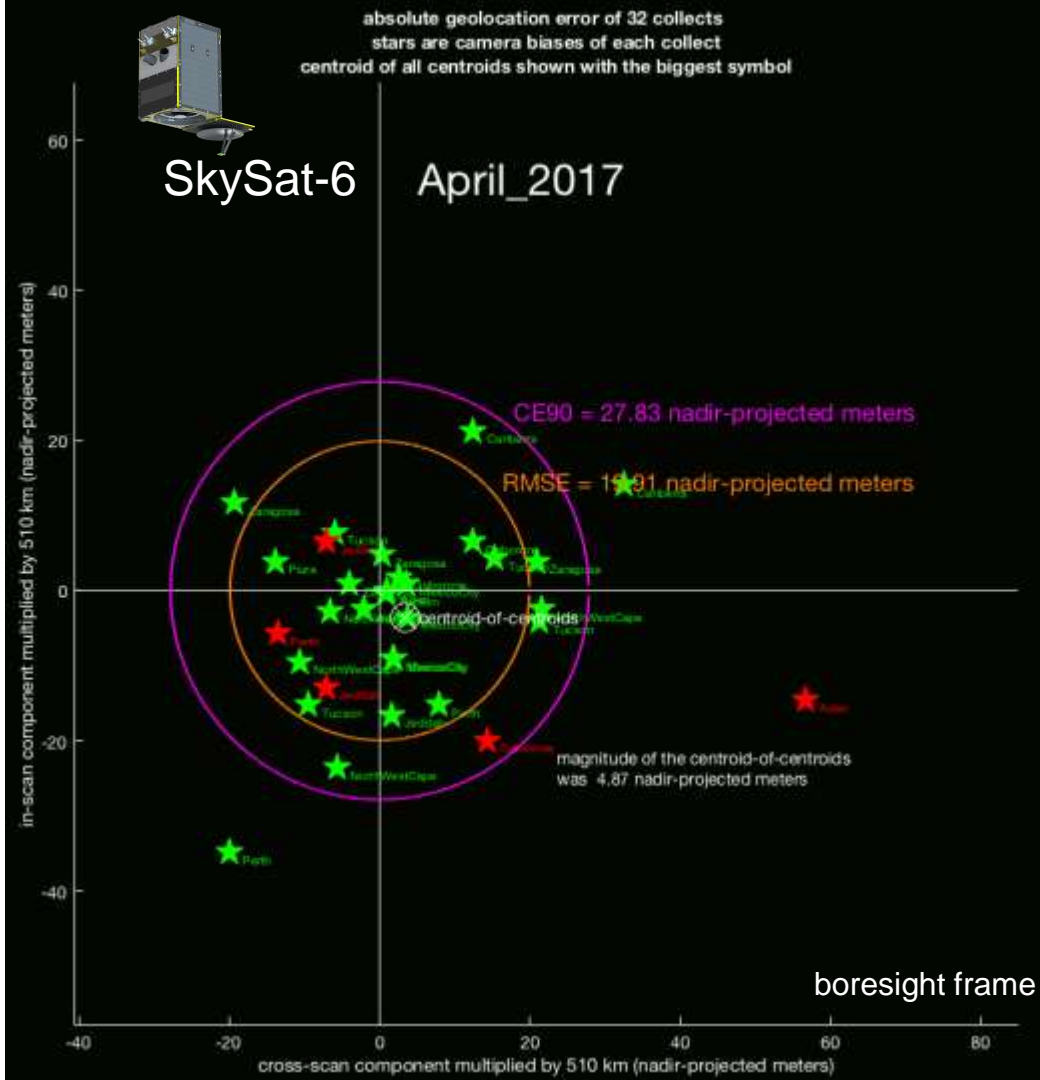
SkySat-3 was stable throughout the 13 month period



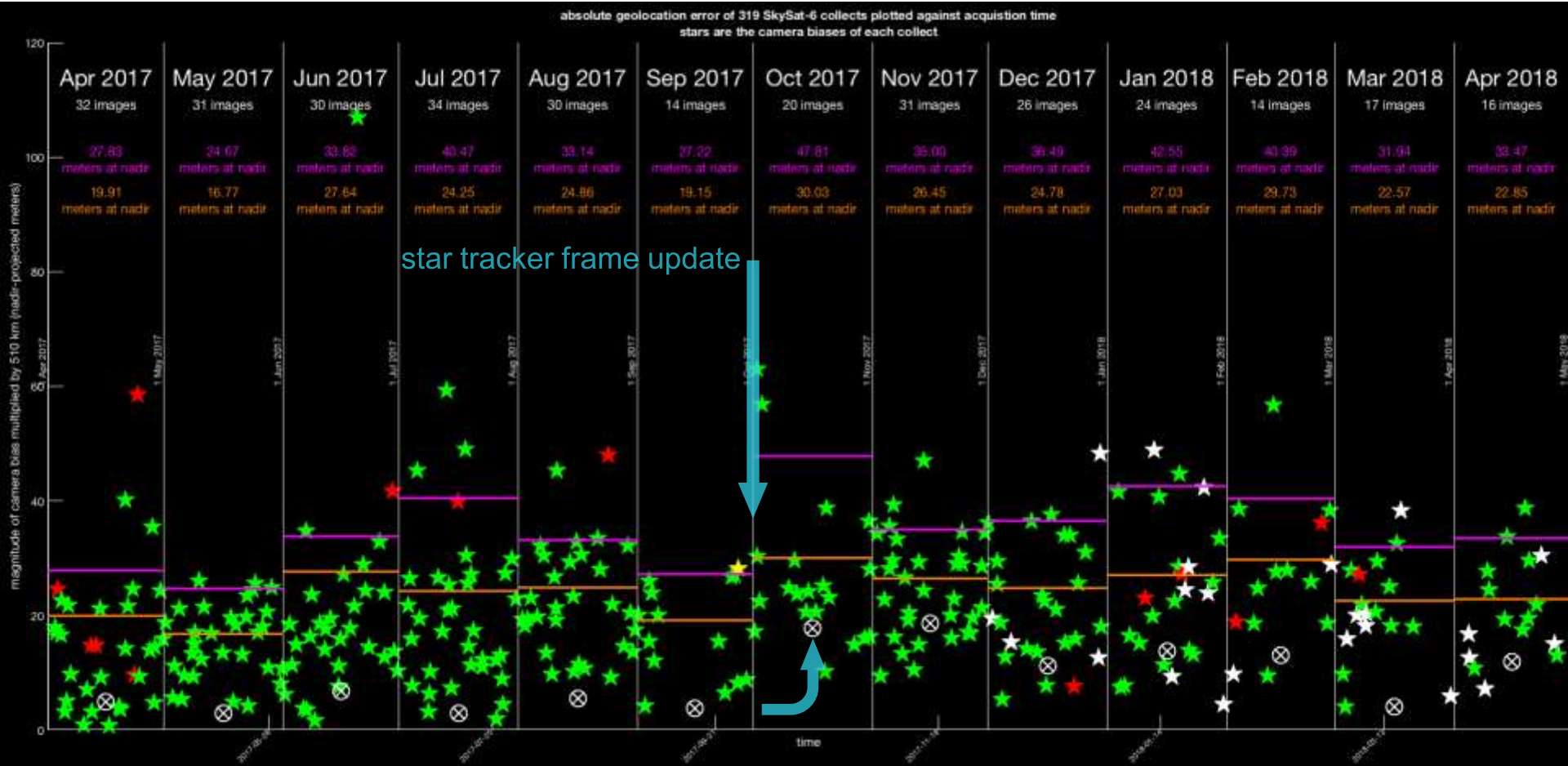
13 months of SkySat-6, ending in April 2018

collect average star color	meaning
white	tracker lock unknown
green	dual tracker lock
yellow	tracker A only
blue	tracker B only
red	"freaky", "unsettled" (obvious Kalman filter problems)

*~18 meter bias appears in Oct 2017,
after a star tracker frame update*



SkySat-6 was stable except for a small bias appearing in Oct



An aerial photograph of Singapore, showing a dense urban landscape with a grid-like street pattern. The city is situated along a coastline, with a large body of water (the Singapore Strait) visible on the right side. The water is dark blue and contains many small white boats. A large, white, dome-shaped building is visible on the left side of the image. The text "low precision methods" is overlaid in white on a dark rectangular background in the upper left quadrant.

low precision methods

Singapore Strait, Singapore – July 29, 2016



we can trade precision for automation

- high precision = requires Byron's time
 - (now with 13 satellites, that's **ALL** Byron's time!)
- given the geometric stability, this suggests we can downgrade to a **completely automated** alternative for routine monitoring
- adjustment performed by the production system fits the bill, but is **low precision**



Kokpatas, Mine, Uzbekistan

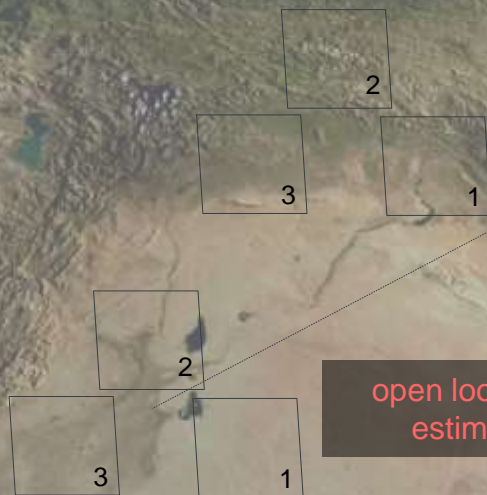


examine the delta between open and closed loop georeferencing

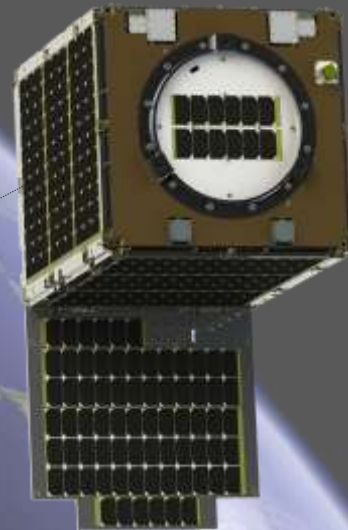
The Planet image processing pipeline adjusts imagery into alignment with the base layer, removing:

- up to 1 km of translation (roll, pitch)
- up to +/- 8° of yaw

and storing adjusted RPCs



closed loop "projection",
adjusted RPCs



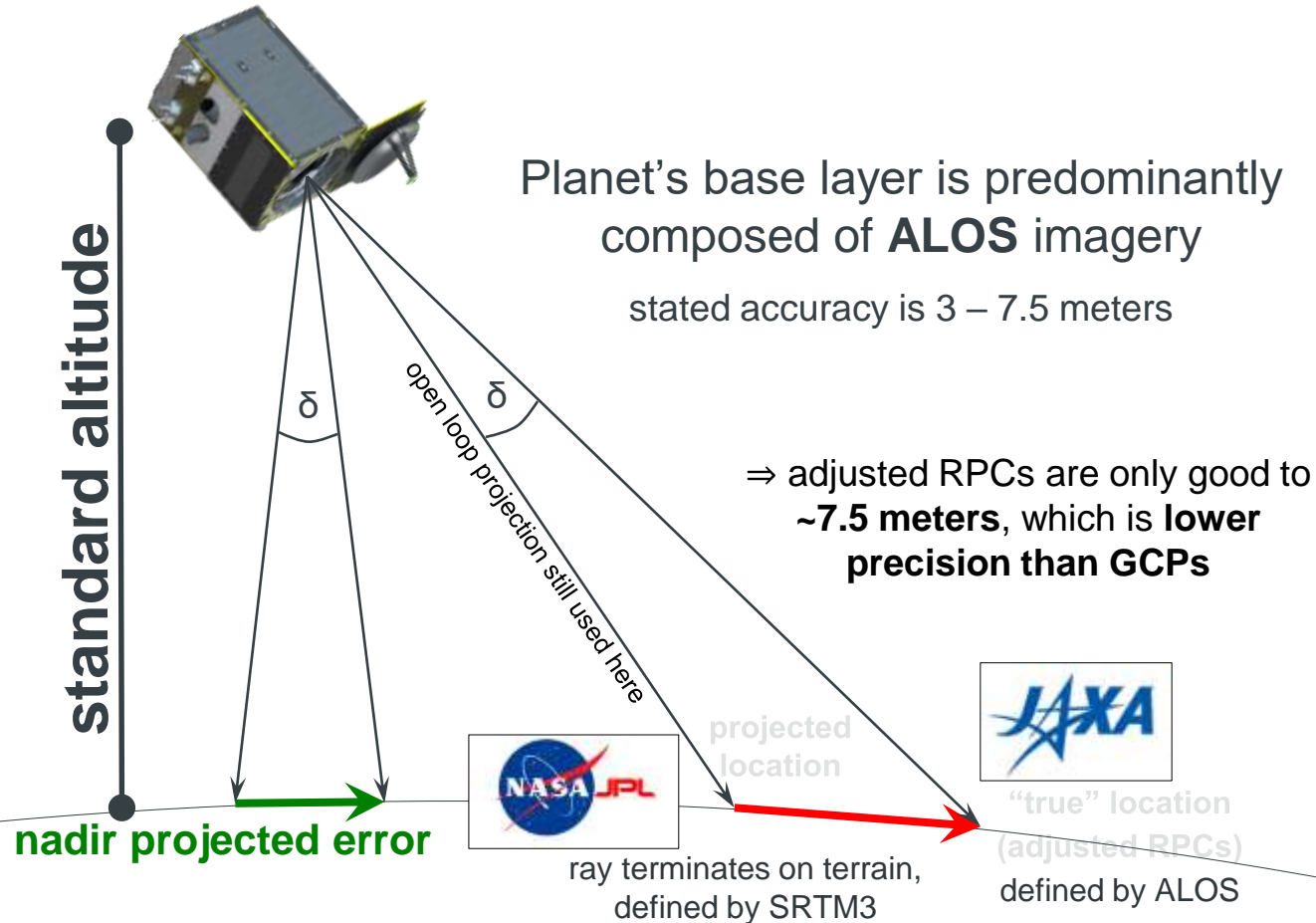
* For more details, see my
ASPRS 2018 presentation

the adjusted RPCs can be used as truth instead of GCPs

nadir projection is used to compare collects with different off nadir angles

SkySat	standard altitude (km)
1	600
2	635
3...13	510

scaling factors **not** updated over time, to keep past results fixed



we can readily test low precision methods

*test if both high and low precision methods
get the same geolocation error for a
single collect*

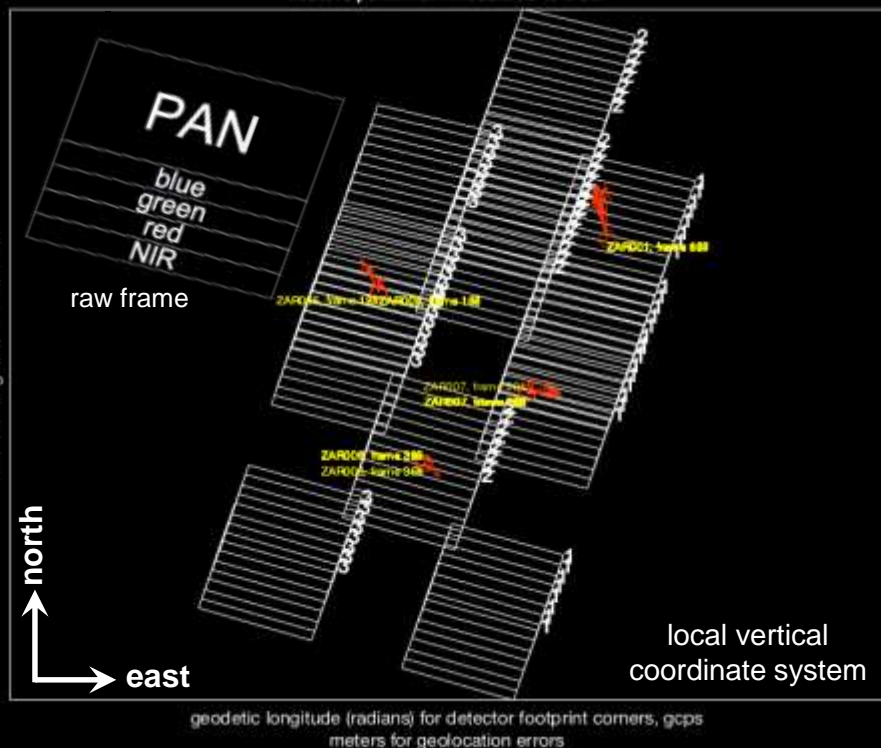


despite the differences, the results compare well

Zaragoza collect **s108_20180722T132530Z**

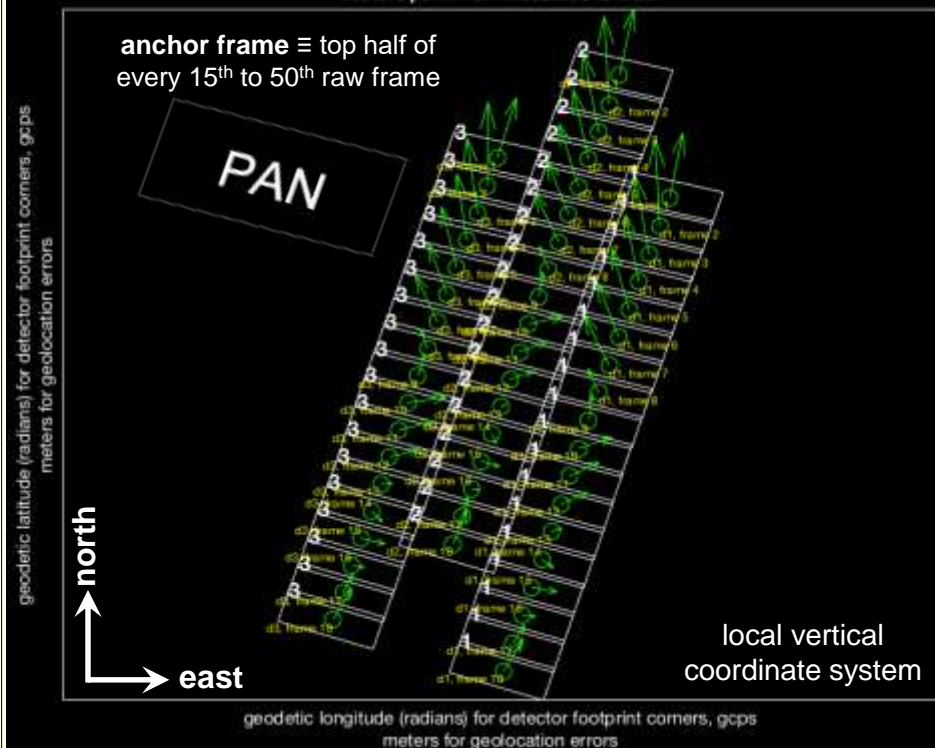
marked GCPs in raw frames (high precision)

SkySat-10 absolute geolocation errors plotted in the local vertical coordinate system
vectors point from measured to truth



using adjusted RPCs with anchor frames (low precision)

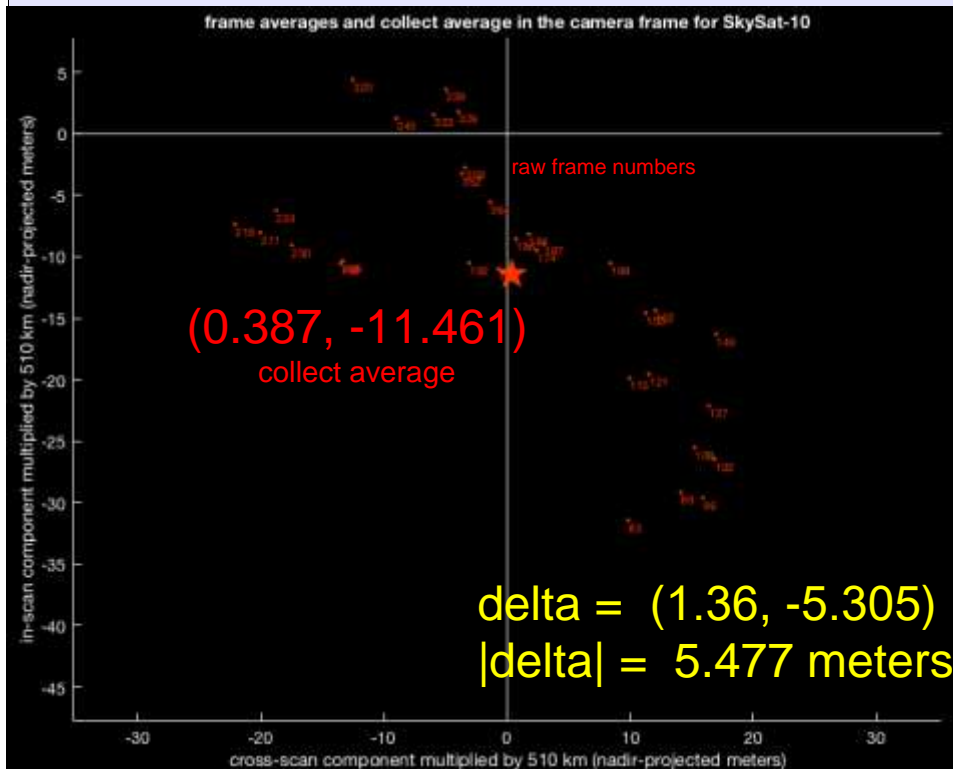
SkySat-10 absolute geolocation errors plotted in the local vertical coordinate system
vectors point from measured to truth



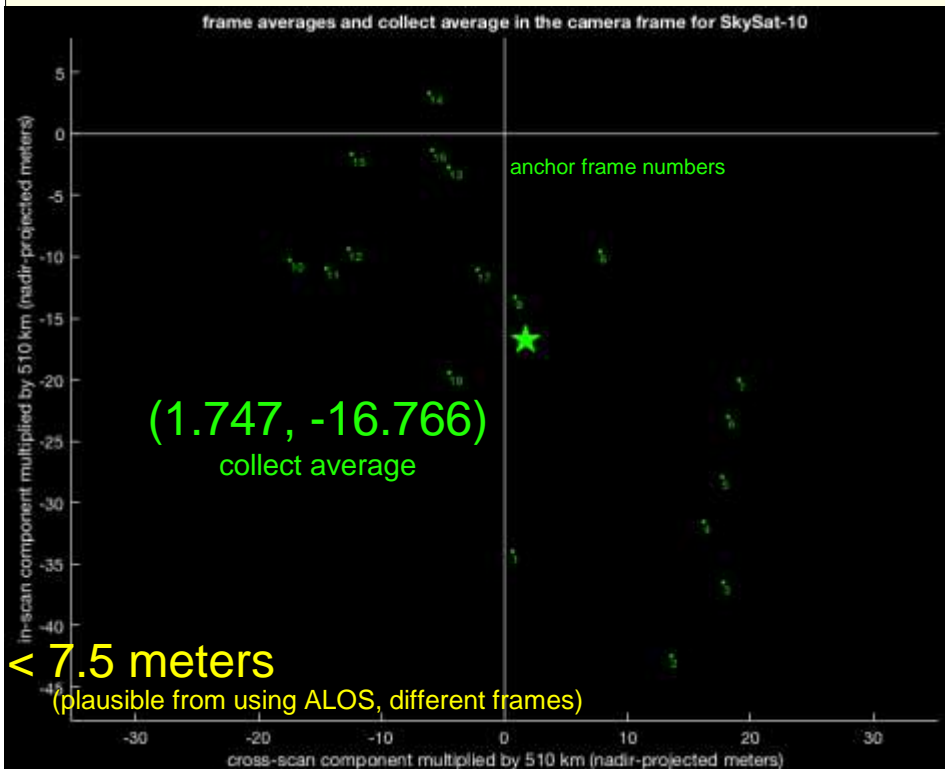
despite the differences, the results compare well

Zaragosa collect s108_20180722T132530Z

marked GCPs in raw frames (high precision)



using adjusted RPCs with anchor frames (low precision)



$< 7.5 \text{ meters}$
(plausible from using ALOS, different frames)

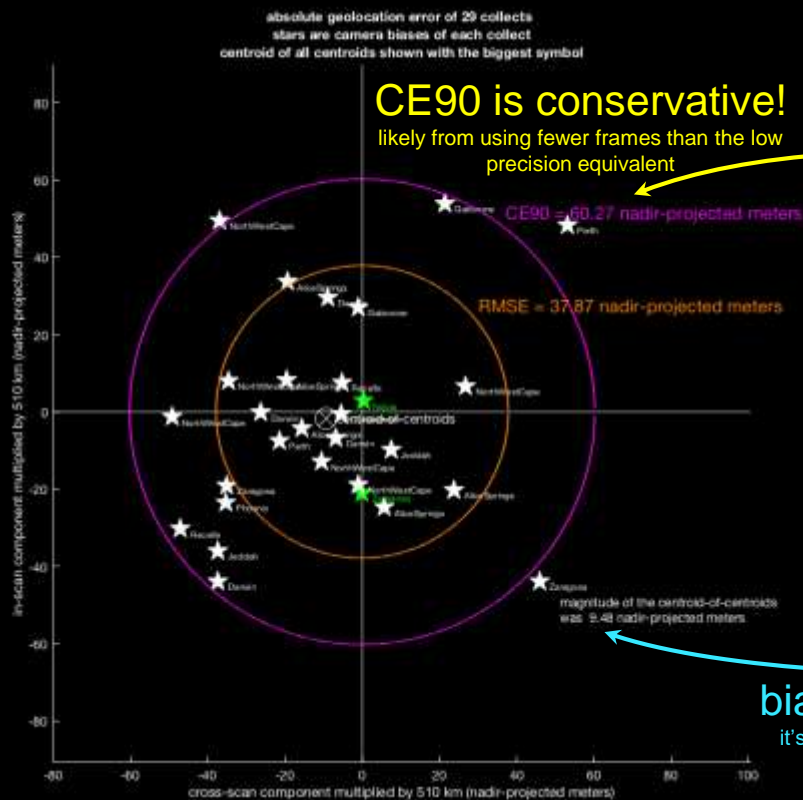
we can readily test low precision methods

*test if both high and low precision methods
get the same geolocation error for a
single month*

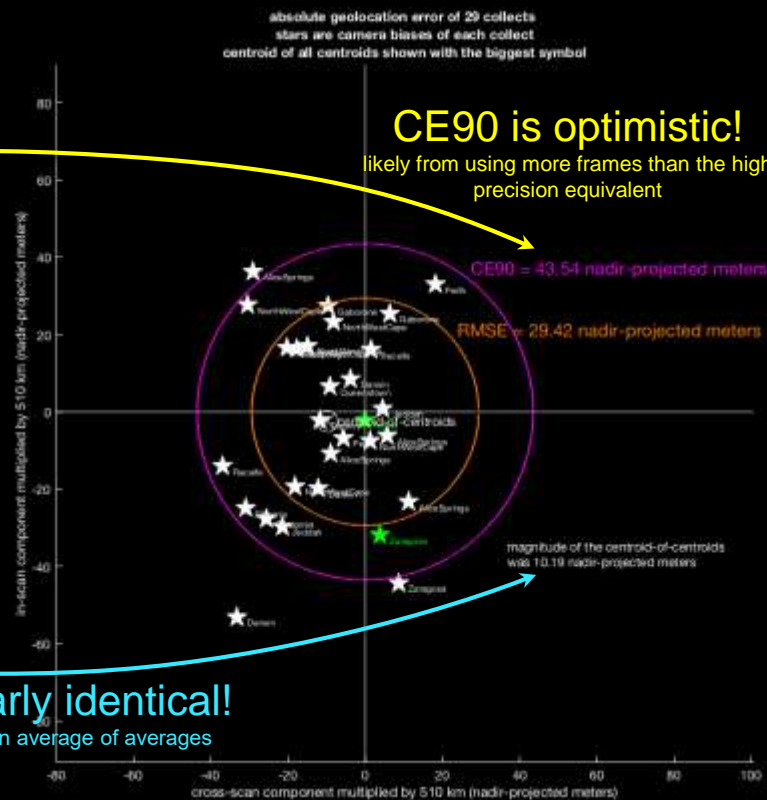
despite the differences, the results compare well

July for SkySat-9

marked GCPs in raw frames (high precision)



using adjusted RPCs with anchor frames (low precision)



bias is nearly identical!
it's hard to move an average of averages

Byron's (new) official approach to geocal

- lowPrecision methods are a fast way to know which SkySats need help
- only SkySats in need require GCP methods
- note how **|bias|** is monitored, not **|CE90|**
- note how the threshold for intervention goes as 1% of the swathWidth:

SkySat	approximate swathWidth at nadir (km)	swathWidth*0.01 (m)
1	8.0	80
2	8.0	80
3...13	6.7	67

MATLAB

```
% loop over all SkySats
for SkySat = 1:13

    % have an initial look using low precision methods
    [ ce90 bias ] = lowPrecision_assess(SkySat, 'Aug', 2018);

    if (norm(bias) < swathWidth(SkySat)*0.01)

        % ignore well behaved SkySats
        continue

    end

    % have a closer look using GCPs
    [ ce90 bias ] = GCP_assess(SkySat, 'Aug', 2018);

    if (norm(bias) < swathWidth(SkySat)*0.01)

        % ignore well behaved SkySats
        continue

    end

    % deduce the boresight correction using GCPs
    q_betterBore2oldBore = GCP_correct(SkySat, 'Aug', 2018);

end
```

low precision results

London Array Wind Farm, United Kingdom – April 17, 2016



**low precision methods can be leveraged
immediately**

monthly performance for selected Skysats,
for last month (August 2018),

just because it's easy



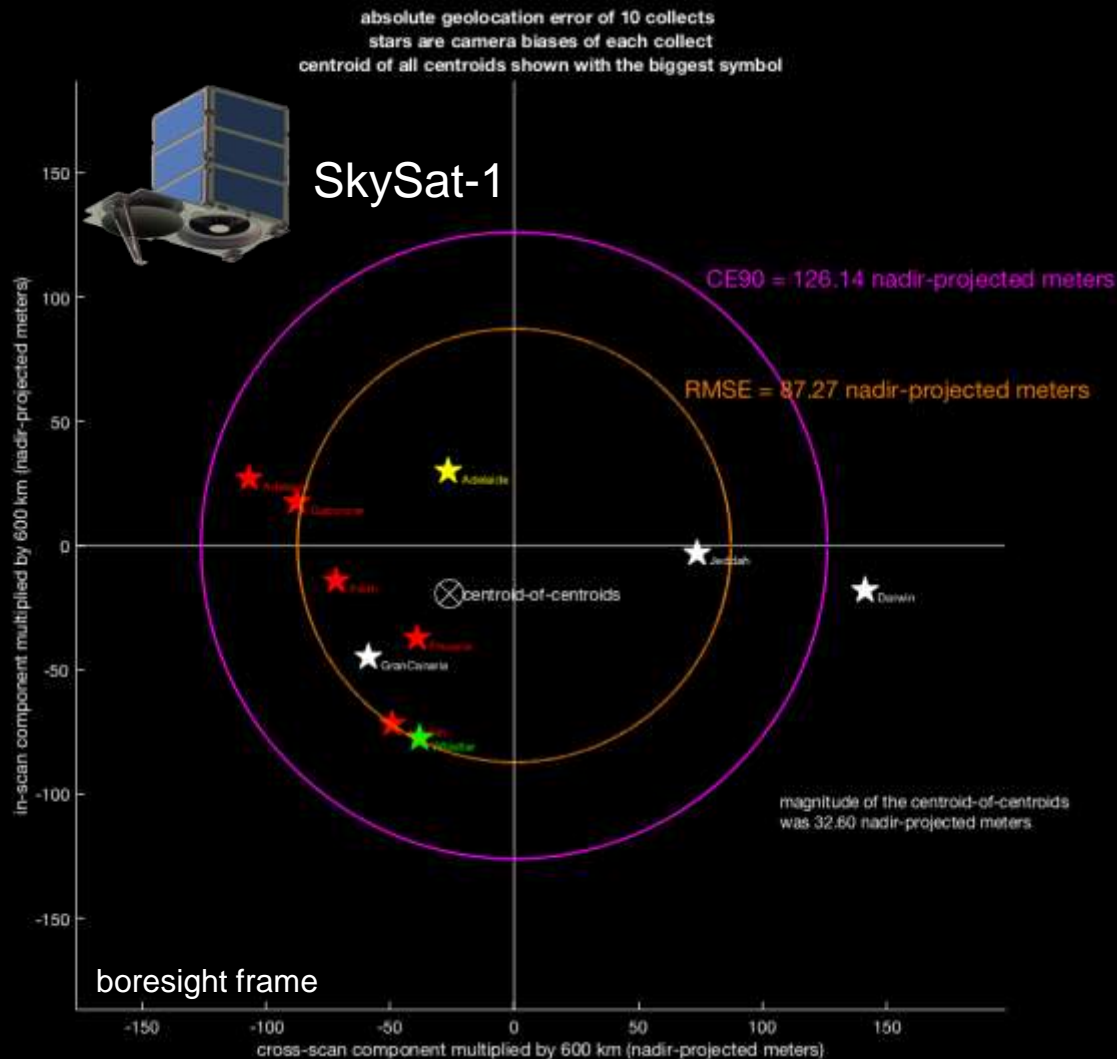
Chaudière River, Canada



SkySat-1, August 2018

collect average star color	meaning
white	tracker lock unknown
green	dual tracker lock
yellow	tracker A only
blue	tracker B only
red	"freaky", "unsettled" (obvious Kalman filter problems)

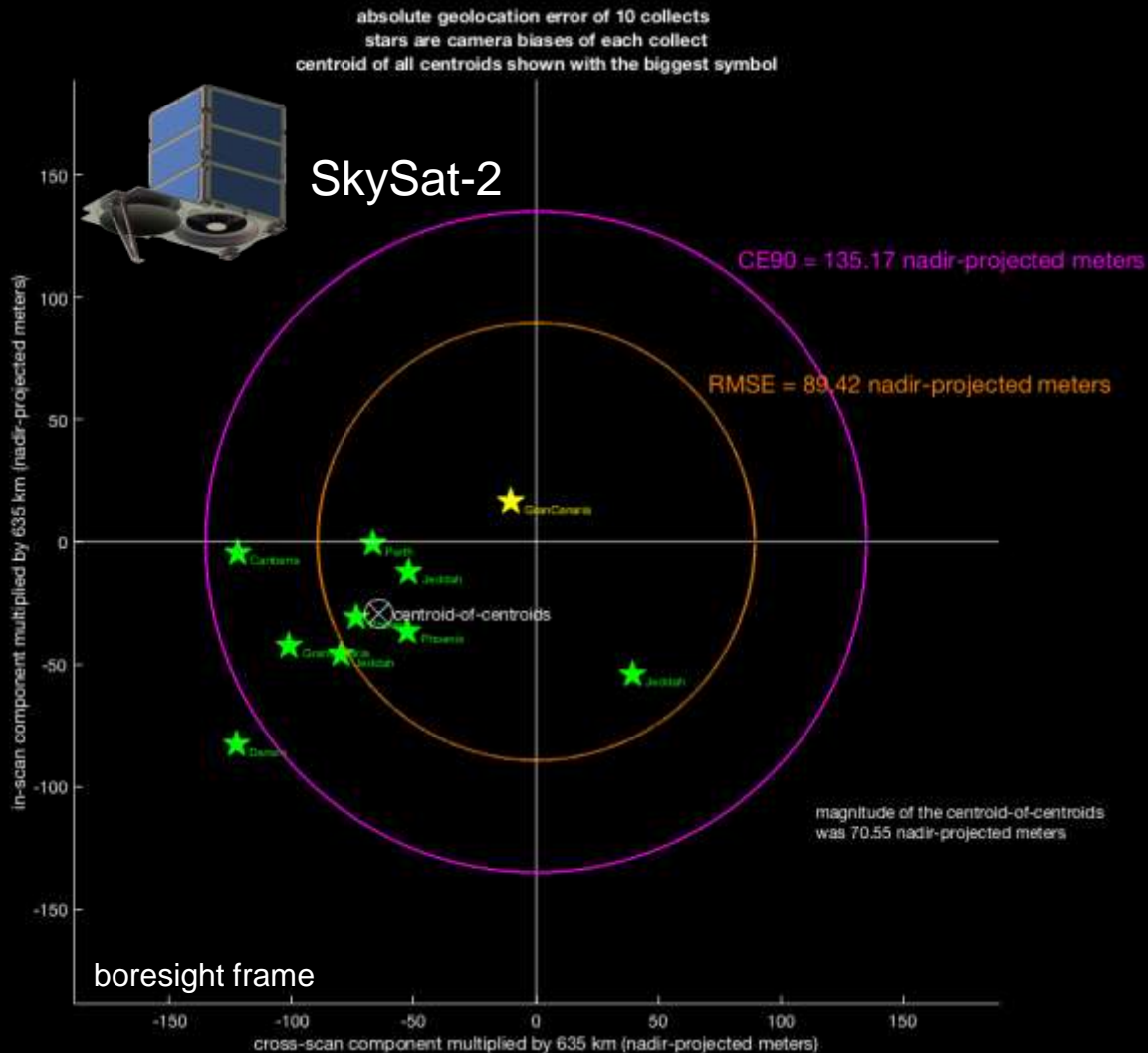
*still hanging in there,
to this day...*



SkySat-2, August 2018

collect average star color	meaning
white	tracker lock unknown
green	dual tracker lock
yellow	tracker A only
blue	tracker B only
red	"freaky", "unsettled" (obvious Kalman filter problems)

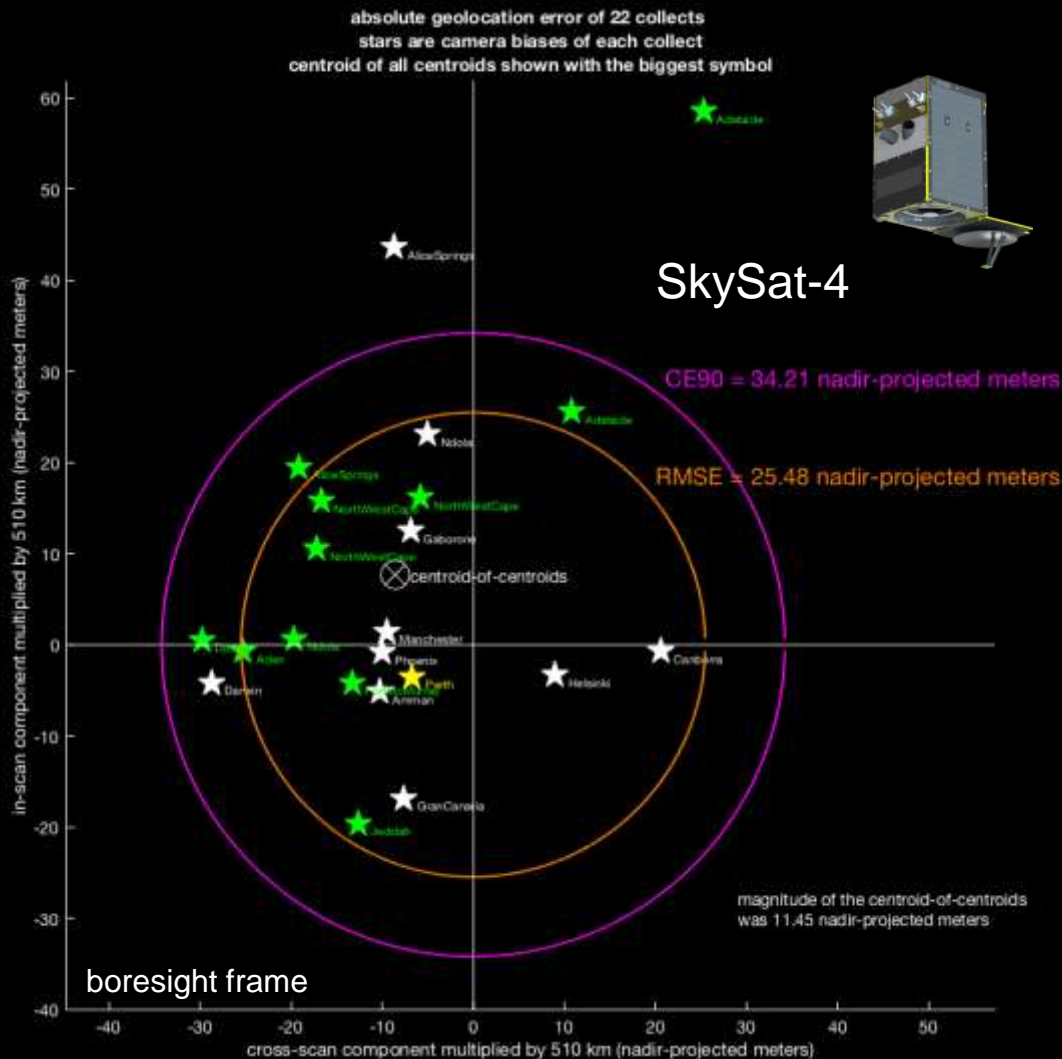
*the bias is large enough to be
significant, but tolerable*



SkySat-4, August 2018

collect average star color	meaning
white	tracker lock unknown
green	dual tracker lock
yellow	tracker A only
blue	tracker B only
red	"freaky", "unsettled" (obvious Kalman filter problems)

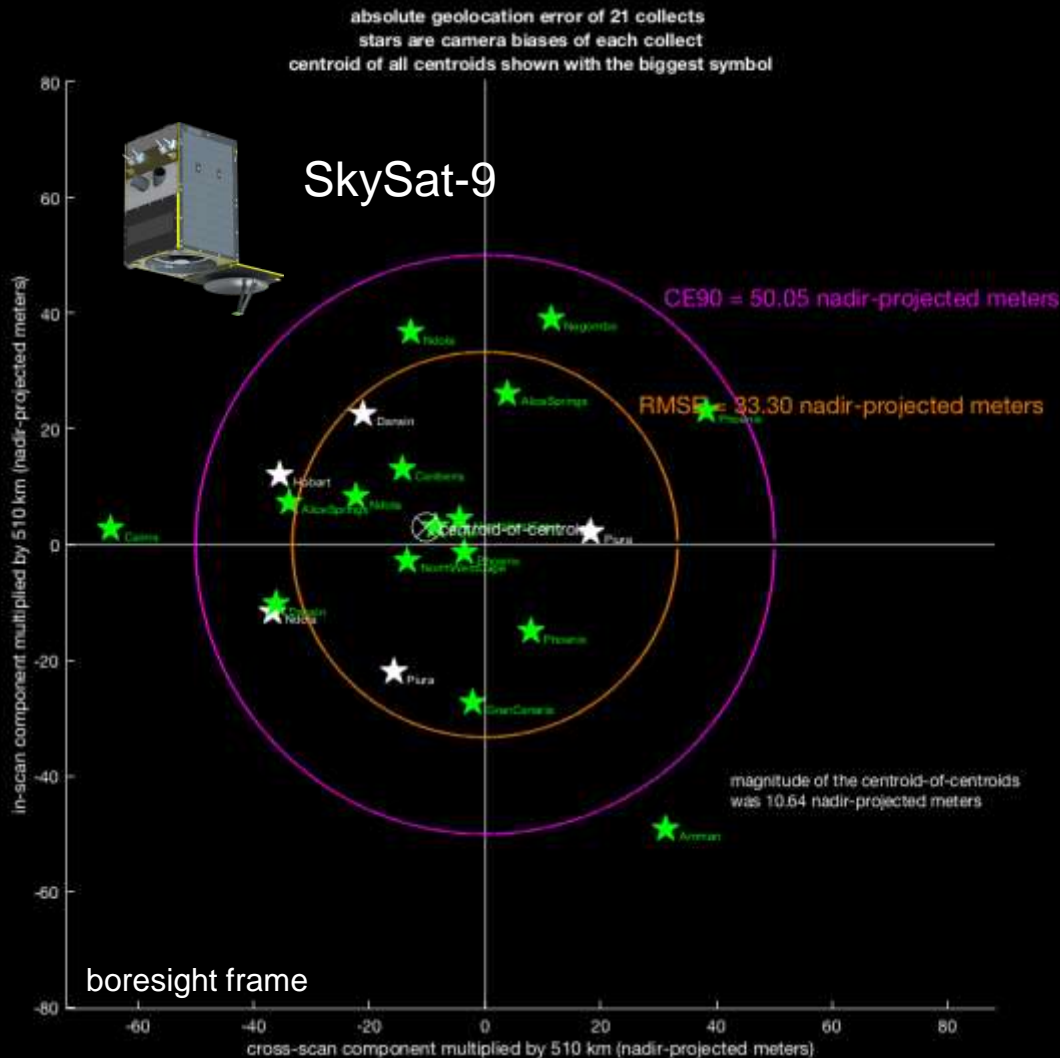
unbiased! No problems to fix!



SkySat-9, August 2018

collect average star color	meaning
white	tracker lock unknown
green	dual tracker lock
yellow	tracker A only
blue	tracker B only
red	"freaky", "unsettled" (obvious Kalman filter problems)

unbiased! No problems to fix!



An aerial photograph of the Great Barrier Reef, showing the intricate patterns of the coral and the surrounding ocean. A semi-transparent dark rectangle is overlaid on the upper left portion of the image, containing the word "conclusions" in white text.

conclusions

Great Barrier Reef, Australia – July 8, 2016



conclusions

- Planet's SkySats are geometrically stable
- Planet has **high precision** methods for analyzing geolocation error
 - problems found and fixed with GCPs
- Now, Planet also has **low precision** methods for analyzing geolocation error
 - problems can be found faster than with GCPs*
 - problems are still fixed with GCPs (!)

* because Byron insists on 1 pixel marking accuracy



Khe Solar One, South Africa

